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Heisenberg scaling based on population coding

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1 State estimation

To see the standard scaling for the mutual information, we consider state estimation, i.e., we focus on a d -parameter state family $\{\rho_\theta\}_{\theta \in \Theta}$ on the Hilbert space \mathcal{H}_A , where Θ is a subset of \mathbb{R}^d . We consider a Bayesian prior μ on Θ . We denote the set of density matrices on \mathcal{H} by $\mathcal{S}(\mathcal{H})$. We denote the classical system Θ by B . We consider n -copy state $\rho_\theta^{\otimes n}$. We have classical-quantum state

$$\rho_{AB} := \int_{\Theta} \rho_\theta^{\otimes n} \otimes |\theta\rangle\langle\theta| \mu(d\theta). \quad (1.1)$$

We focus on the mutual information between A and B , which is given as

$$I(A; B) = S(\rho_A) - \int_{\Theta} S(\rho_\theta^{\otimes n}) \mu(d\theta) = \int_{\Theta} D(\rho_\theta^{\otimes n} \| \rho_A) \mu(d\theta), \quad (1.2)$$

where $S(\rho)$ expresses the von Neumann entropy $-\text{Tr} \rho \log \rho$ of ρ , and $D(\rho \| \sigma)$ expresses the quantum relative entropy $\text{Tr} \rho(\log \rho - \log \sigma)$.

When all densities are commutative, i.e., the model is classical, the references [31, 32] showed that

$$I(A; B) = \frac{d}{2} \log n + O(1). \quad (1.3)$$

When our model $\{\rho_\theta\}_{\theta \in \Theta}$ is the full model on t -dimensional system and μ is invariant for unitary action, the reference [33] showed that

$$I(A; B) = \frac{t^2 - 1}{2} \log n + O(1). \quad (1.4)$$

Since the number of parameters of the full model is $t^2 - 1$, (1.4) can be considered as a generalization of (1.3). When a model satisfies a certain condition, using the result by [36], we can show

$$I(A; B) = \frac{d}{2} \log n + o(\log n). \quad (1.5)$$

That is, the leading term is the number of parameters times $\frac{1}{2} \log n$.

We back to the spirit of population coding, and focus on the number $N(\{\rho_\theta^{\otimes n}\}_{\theta \in \Theta}, \epsilon)$ of distinguishable states among $\{\rho_\theta^{\otimes n}\}_{\theta \in \Theta}$ with the average decoding error probability $\epsilon > 0$. As shown in [44, (4.32)], using Fano inequality, we can evaluate this number as

$$\log N(\{\rho_\theta^{\otimes n}\}_{\theta \in \Theta}, \epsilon) \leq \frac{\log 2 + I(A; B)}{1 - \epsilon}. \quad (1.6)$$

That is, the relations (1.3), (1.4), and (1.5) give upper bounds of this number.

2 General problem formulation

2.1 General description

Let G be a compact group and μ be the Haar measure of G . We focus on a unitary representation f of G over a finite-dimensional Hilbert space. For this aim, we choose an input state. We assume that any entangled input state with any reference system is available. To consider this problem, we denote the set of the labels of irreducible representations of G by \hat{G} . Let \mathcal{U}_λ be the irreducible representation space identified by $\lambda \in \hat{G}$, and d_λ be its dimension.

We also define the twirling operation for the group G as

$$\mathcal{T}_G(\rho) := \int_G f(g') \rho f(g')^\dagger \mu(dg'). \quad (2.1)$$

We denote the set of irreducible representations appearing in f by \hat{G}_f . We decompose the representation system \mathcal{H}_A as follows.

$$\mathcal{H}_A = \bigoplus_{\lambda \in \hat{G}_f} \mathcal{U}_\lambda \otimes \mathbb{C}^{n_\lambda}, \quad (2.2)$$

where n_λ expresses the multiplicity of the representation space \mathcal{U}_λ .

When a reference system \mathbb{C}^l is available, we have

$$\mathcal{H}_{Al} := \mathcal{H}_A \otimes \mathbb{C}^l = \bigoplus_{\lambda \in \hat{G}_f} \mathcal{U}_\lambda \otimes \mathbb{C}^{ln_\lambda}. \quad (2.3)$$

However, when the input state is a pure state, the orbit is restricted to the following space by choosing a suitable subspace $\mathbb{C}^{\min(d_\lambda, ln_\lambda)}$ of \mathbb{C}^{ln_λ} . That is, our representation space can be considered as follows.

$$\bigoplus_{\lambda \in \hat{G}_f} \mathcal{U}_\lambda \otimes \mathbb{C}^{\min(d_\lambda, ln_\lambda)}. \quad (2.4)$$

When $l \geq d_\lambda/n_\lambda$ for any $\lambda \in \hat{G}_f$, our representation is given as

$$\mathcal{H}_{AR} := \bigoplus_{\lambda \in \hat{G}_f} \mathcal{U}_\lambda \otimes \mathbb{C}^{d_\lambda}. \quad (2.5)$$

In the following, we consider the above case. We denote the projection to $\mathcal{U}_\lambda \otimes \mathbb{C}^{d_\lambda}$ by P_λ .

2.2 Mutual information

We choose an input state ρ and a distribution P on the system $\mathcal{B} = G$, where the random choice of \mathcal{B} is denoted by the random variable B . So, we have a classical-quantum state $\sum_{g \in \mathcal{X}} P(g) f(g) \rho f(g)^\dagger \otimes |g\rangle\langle g|$. We focus on the mutual information $I(AI; B)$ or $(AR; B)$, which depends on ρ and P . When ρ is decomposed as $\sum_j q_j \rho_j$, the mutual information is evaluated as

$$\begin{aligned} I(AI; B)[P, \rho] &:= S\left(\sum_{g' \in \mathcal{X}} P(g') f(g') \rho f(g')^\dagger\right) - \sum_{g \in \mathcal{X}} P(g) S\left(f(g) \rho f(g)^\dagger\right) \\ &= \sum_{g \in \mathcal{X}} P(g) D\left(f(g) \rho f(g)^\dagger \parallel \sum_{g' \in \mathcal{X}} P(g') f(g') \rho f(g')^\dagger\right) \\ &\leq \sum_j q_j \sum_{g \in \mathcal{X}} P(g) D\left(f(g) \rho_j f(g)^\dagger \parallel \sum_{g' \in \mathcal{X}} P(g') f(g') \rho_j f(g')^\dagger\right). \quad (2.6) \end{aligned}$$

The final inequality follows from the joint convexity of relative entropy. Since any mixed state can be written as a mixture of pure states, to maximize the mutual information, we can restrict the input state as an input pure state

$|\psi\rangle = \oplus_{\lambda \in \hat{G}_f} \sqrt{p_\lambda} |\psi_\lambda\rangle$. In this case, since the von Neumann entropy of a pure state is zero, the mutual information is given as the von Neumann entropy of the mixture of

the final states.

$$I(AI; B)[P, |\psi\rangle] = S\left(\sum_{g' \in \mathcal{X}} P(g') f(g') |\psi\rangle \langle \psi| f(g')^\dagger\right). \quad (2.7)$$

We consider the following optimization problem.

$$I(G)_{AI} := \max_{|\psi\rangle} \max_P I(AI; B)[P, |\psi\rangle]. \quad (2.8)$$

As shown in [45], due to the convexity of von Neumann entropy the maximum is attained by the Haar measure μ . Hence,

$$\max_P I(AI; B)[P, |\psi\rangle] = I(AI; B)[\mu, |\psi\rangle] = S(\mathcal{T}_G(|\psi\rangle \langle \psi|)), \quad (2.9)$$

which implies

$$I(G)_{AI} = \max_{|\psi\rangle} S(\mathcal{T}_G(|\psi\rangle \langle \psi|)). \quad (2.10)$$

Here, we set $|\phi_\lambda\rangle$ to be a pure state $\mathcal{U}_\lambda \otimes \mathbb{C}^{\min(d_\lambda, l n_\lambda)}$ such that $\text{Tr}_{\mathcal{U}_\lambda} |\phi_\lambda\rangle \langle \phi_\lambda|$ is the completely mixed state on $\mathbb{C}^{\min(d_\lambda, l n_\lambda)}$. Such a state $|\phi_\lambda\rangle$ is called the maximally entangled state on $\mathcal{U}_\lambda \otimes \mathbb{C}^{\min(d_\lambda, l n_\lambda)}$.

When $|\psi\rangle$ is the state $|\phi(p)\rangle := \sum_{\lambda \in \hat{G}_f} \sqrt{p_\lambda} |\phi_\lambda\rangle$, where p is a distribution on \hat{G}_f , we have

$$\begin{aligned} S(\mathcal{T}_G(|\phi(p)\rangle\langle\phi(p)|)) &= S\left(\sum_{\lambda \in \hat{G}_f} p_\lambda \frac{P_\lambda}{d_\lambda \min(n_\lambda, d_\lambda)}\right) \\ &= S(p) + \sum_{\lambda \in \hat{G}_f} p_\lambda \log(d_\lambda \min(n_\lambda, d_\lambda)). \end{aligned} \quad (2.11)$$

Since the dimension of support of $\mathcal{T}_G(|\psi\rangle\langle\psi|)$ is upper bounded by $\sum_{\lambda \in \hat{G}} d_\lambda \min(n_\lambda, d_\lambda)$, we have

$$I(X; Al)[\mu, |\psi\rangle] = S(\mathcal{T}_G(|\psi\rangle\langle\psi|)) \leq R(G)_{Al} := \log\left(\sum_{\lambda \in \hat{G}_f} d_\lambda \min(ln_\lambda, d_\lambda)\right). \quad (2.12)$$

The equality holds when the input state is $|\phi(p)\rangle$ and $p_\lambda = \frac{d_\lambda \min(ln_\lambda, d_\lambda)}{\sum_{\lambda' \in \hat{G}_f} d_{\lambda'} \min(ln_{\lambda'}, d_{\lambda'})}$.

Therefore, we have

$$I(G)_{Al} = \log\left(\sum_{\lambda \in \hat{G}_f} d_\lambda \min(ln_\lambda, d_\lambda)\right). \quad (2.13)$$

Overall, the optimal input state is

$$\sum_{\lambda \in \hat{G}_f} \sqrt{\frac{d_\lambda \min(\ln n_\lambda, d_\lambda)}{\sum_{\lambda' \in \hat{G}_f} d_{\lambda'} \min(\ln n_{\lambda'}, d_{\lambda'})}} |\phi_\lambda\rangle. \quad (2.14)$$

In particular, when l satisfies the condition $l \geq d_\lambda/n_\lambda$ for any $\lambda \in \hat{G}_f$,

$$I(G)_{AR} = I(G)_{Al} = R(G)_{AR} := \log \left(\sum_{\lambda \in \hat{G}_f} d_\lambda^2 \right). \quad (2.15)$$

2.3 Number of distinguishable elements

Next, we consider how many elements in G can be distinguished via the above process. When the input state is ρ , we denote the number of distinguishable states among $\{f(g)\rho f(g)^\dagger\}_{g \in G}$ with the average decoding error $\epsilon > 0$ by $M_{Al}(\rho, \epsilon)$. That is,

$$M_{Al}(\rho, \epsilon) := \max \left\{ M \left| \begin{array}{l} \frac{1}{M} \sum_{j=1}^M \text{Tr } f(g_j)\rho f(g_j)^\dagger \Pi_j \\ \geq 1 - \epsilon \end{array} \right. \right\}, \quad (2.16)$$

where the maximum in (2.16) is taken with respect to $M, g_1, \dots, g_M \in G, \{\Pi_j\}_{j=1}^M$.

We consider the following optimization problems.

$$M_\epsilon(G)_{Al} := \max_{\rho} M_{Al}(\rho, \epsilon). \quad (2.17)$$

We have

$$\log M(|\psi\rangle, \epsilon) \geq \max_P S_\alpha \left(\sum_{g' \in \mathcal{X}} P(g') f(g') |\psi\rangle \langle \psi| f(g')^\dagger \right) - \frac{1}{\alpha - 1} (\log 2 - \log \epsilon), \quad (2.18)$$

$$\log M(|\psi\rangle, \epsilon) \leq \max_P S_\beta \left(\sum_{g' \in \mathcal{X}} P(g') f(g') |\psi\rangle \langle \psi| f(g')^\dagger \right) + \frac{1}{\beta - 1} \log(1 - \epsilon) \quad (2.19)$$

for $0 < \beta < 1$ and $1 < \alpha \leq 2$. For its detailed derivation, see Appendix AppendixA. The above maximum is attained when P is the Haar measure μ . Since the dimension of support of $\mathcal{T}_G(|\psi\rangle\langle\psi|)$ is upper bounded by $\sum_{\lambda \in \hat{G}} d_\lambda \min(n_\lambda, d_\lambda)$, we have

$$S_\alpha(\mathcal{T}_G(|\psi\rangle\langle\psi|)) \leq R(G)_{Al}. \quad (2.20)$$

The equality holds when the input state is $|\phi\rangle$. Thus, choosing the best choice $\alpha = 2$ and taking the limit $\beta \rightarrow +0$, we have

$$R(G)_{Al} - (\log 2 - \log \epsilon) \leq \log M_\epsilon(G)_{Al} \leq R(G)_{Al} - \log(1 - \epsilon). \quad (2.21)$$

In particular, we have

$$R(G)_{AR} - (\log 2 - \log \epsilon) \leq \log M_\epsilon(G)_{AR} \leq \log R(G)_{AR} - \log(1 - \epsilon). \quad (2.22)$$

Therefore, when $1 > \epsilon > 0$ is fixed, $\log R(G)_{AR}$ is the dominant term.

3 Multiple phase estimation

Here, we consider the multi-phase application model on the t -dimensional system \mathcal{H}_A spanned by $\{|j\rangle\}_{j=0}^{t-1}$. This model is given as the application of the group $MP_{t-1} := \{U_\theta\}_{\theta \in [0, 2\pi)^{t-1}}$, where the unitary U_θ is defined as $|0\rangle\langle 0| + \sum_{j=1}^{t-1} e^{i\theta_j} |j\rangle\langle j|$. Now, we consider the n -parallel application of U_θ on $\mathcal{H}_{A^n} := \mathcal{H}_A^{\otimes n}$. In this representation, all irreducible representations are characterized by the combinatorics \mathcal{C}_t^n , which is defined as

$$\mathcal{C}_t^n := \left\{ \vec{n} := (n_0, n_1, \dots, n_{t-1}) \in \mathbb{N}^t \left| \sum_{j=0}^{t-1} n_j = n \right. \right\}, \quad (3.1)$$

where \mathbb{N} is the set of non-negative integers. Since all irreducible representations are one-dimensional, $d_{\vec{n}} = 1$ for $\vec{n} \in \mathcal{C}_t^n$ so that we do not need to attach any reference system, i.e., $R(G)_{A1} = R(G)_{AR}$. Since $|\mathcal{C}_t^n| = \binom{n+t-1}{t-1}$, we have

$$I(MP_{t-1})_{A^n} = R(MP_{t-1})_{A^n} = \log \binom{n+t-1}{t-1} = (t-1) \log n + o(1) \quad (3.2)$$

while the number of our parameters is $t-1$. Compare with (1.5), (3.2) achieves the twice of the state estimation case.

When $t = 2$, the optimal input state is

$$\sum_{j=0}^n \frac{1}{\sqrt{n+1}} |\overbrace{0 \dots 0}^j \overbrace{1 \dots 1}^{n-j}\rangle. \quad (3.3)$$

The asymptotic estimation error with the above input state has been studied in [46, Sections 3 and 4]. As explained in [19, Section 4], this method is essentially the same as Kitaev's method [48, 49], and has been implemented by [50].

Here, we compare the input state (3.3) with the case with the noon state [9, 8, 7]. The input noon state has only two irreducible representations; the subspace spanned by $|0\rangle^{\otimes n}$ and $|1\rangle^{\otimes n}$. The relations (2.9) and (2.11) imply

$$I(X; A1)[\mu, \frac{1}{\sqrt{2}}(|0\rangle^{\otimes n} + |1\rangle^{\otimes n})] = \log 2. \quad (3.4)$$

The input noon state has quite small global information, which certifies the impossibility of global estimation by the input noon state.

When we focus on the error $\sin^2 \frac{\theta_{guess} - \theta_{true}}{2}$, the input state (3.3) does not coincide with the optimal input. Further, the input state (3.3) does not achieve Heisenberg limit in this sense, but the input state (3.3) achieves the Heisenberg scaling in the sense limiting distribution.

4 n -tensor product representation of $SU(t)$ on $\mathcal{H}_A = \mathbb{C}^t$

Y_t^n : Set of Semistandard Young tableau.

$\mathcal{M}_\lambda = \mathbb{C}^{n_\lambda}$: Multiplicity space of Irreducible Unitary Representation U^λ with Multiplicity n_λ .

Our representation space:

$$\mathcal{H}_{A^n} = \bigoplus_{\lambda \in Y_t^n} \mathcal{H}_\lambda \otimes \mathcal{M}_\lambda. \quad (4.1)$$

When $\lambda = (\lambda_1, \dots, \lambda_t)$ with $\lambda_1 \leq \dots \leq \lambda_t$ and $\sum_j \lambda_j = n$, $d_\lambda := \dim \mathcal{H}_\lambda$ is given as

$$d_\lambda = \prod_{1 \leq j < k \leq t} \frac{k - j + \lambda_k - \lambda_j}{k - j}. \quad (4.2)$$

It is upper bounded by $(n+1)^{t(t-1)/2}$. When the reference system \mathbb{C}^l is sufficiently large in the sense of (2.5), the maximum mutual information is evaluated as

$$\begin{aligned} I(SU(t))_{A^n R} &= R(SU(t))_{A^n R} = \log \left(\sum_{\lambda' \in Y_t^n} d_{\lambda'}^2 \right) \\ &\leq \log(n+1)^{(t+1)t+(t-1)} = (t^2 - 1) \log(n+1). \end{aligned} \quad (4.3)$$

Due to (2.14), the optimal input state is

$$\sum_{\lambda \in Y_t^n} d_\lambda \sqrt{\left(\sum_{\lambda' \in Y_t^n} d_{\lambda'}^2 \right)^{-1}} |\phi_\lambda\rangle, \quad (4.4)$$

Here, $|\phi_\lambda\rangle$ is the maximally entangled state on $\mathcal{H}_\lambda \otimes \mathcal{M}_\lambda$.

When t is fixed and only n increases, we have

$$\log \left(\sum_{\lambda' \in Y_t^n} d_{\lambda'}^2 \right) = (t^2 - 1) \log n + O(1), \quad (4.5)$$

which is shown in Section 5. Since $t^2 - 1$ is the number of parameters of $\text{SU}(t)$. The leading term in (4.5) is twice of the case of state estimation case given in (1.5).

Therefore, this behavior can be considered to achieve the Heisenberg scaling in the sense of mutual information.

At least, when $t = 2$, we can show the above relation as follows. Consider the case with $t = 2$. When $n = 2m$, we have

$$\sum_{\lambda' \in Y_d^n} d_{\lambda'}^2 = \sum_{k=0}^m (2k+1)^2 = \frac{(m+1)(2m+1)(2m+3)}{3}. \quad (4.6)$$

When $n = 2m - 1$, we have

$$\sum_{\lambda' \in Y_d^n} d_{\lambda'}^2 = \sum_{k=1}^m (2k)^2 = \frac{2m(m+1)(2m+1)}{3}. \quad (4.7)$$

Then, we have

$$\log \left(\sum_{\lambda' \in Y_d^n} d_{\lambda'}^2 \right) = 3 \log n - \log 6 + O\left(\frac{1}{n}\right). \quad (4.8)$$

Here, we compare the above optimal case (4.3),(4.5) with the case of the input state maximizing the trace of Fisher information matrix [11]. The maximally entangled state $|\Phi\rangle$ on the symmetric subspace maximizes the trace of Fisher information matrix [11]. In this case, since the dimension of the symmetric subspace is $\binom{n+t-1}{t-1}$, the relations (2.9) and (2.11) imply

$$I(X; AR)[\mu, |\Phi\rangle] = 2 \log \binom{n+t-1}{t-1} = 2(t-1) \log n + o(1), \quad (4.9)$$

which is much smaller than (4.3),(4.5).

Next, we focus on $M_\epsilon(\text{SU}(t))_{AR}$. Due to (2.22), (4.3), and (4.5), $\log M_\epsilon(\text{SU}(t))_{AR}$ behaves as

$$\log M_\epsilon(\text{SU}(t))_{AR} = (t^2 - 1) \log n + O(1). \quad (4.10)$$

Since $\text{SU}(t)$ is parametrized by $t^2 - 1$ parameters, $B(R)$ scales as $O(R^{t^2-1})$. Since $M_\epsilon(\text{SU}(t))_{AR}$ scales as $O(n^{t^2-1})$, the upper bound of R_ϵ scales as $O(n^{-1})$.

5 Proof of (4.5)

Since we have (4.3), it is sufficient to show

$$\log \left(\sum_{\lambda' \in Y_t^n} d_{\lambda'}^2 \right) \geq (t^2 - 1) \log n + O(1). \quad (5.1)$$

We choose a positive real number a_n such that $\frac{n}{a_n t}$ is an integer. We define the subset $Y_t^n(a_n) \subset Y_t^n$ as

$$Y_t^n(a_n) := \left\{ \lambda \mid \frac{n}{a_n t} \leq \lambda_{k+1} - \lambda_k \text{ for } k = 1, \dots, t-1 \right\}. \quad (5.2)$$

For $\lambda \in Y_t^n(a_n)$, we have

$$\begin{aligned} d_\lambda &= \prod_{1 \leq j < k \leq t} \frac{k - j + \lambda_k - \lambda_j}{k - j} \\ &\geq \frac{1}{t} \prod_{1 \leq j < k \leq t} \frac{\lambda_k - \lambda_j}{t} \geq \prod_{1 \leq j < k \leq t} \frac{n}{a_n t^2} = \left(\frac{n}{a_n t^2} \right)^{\frac{(t-1)t}{2}}. \end{aligned} \quad (5.3)$$

Also, using $m_n := n - \frac{n}{a_n}$, we have

$$|Y_t^n(a_n)| = \binom{m_n + t - 1}{t - 1} \geq \frac{m_n^{t-1}}{(t-1)}. \quad (5.4)$$

Therefore,

$$\begin{aligned}
\sum_{\lambda \in Y_t^n} d_\lambda^2 &\geq \sum_{\lambda \in Y_t^n(a_n)} d_\lambda^2 \geq \sum_{\lambda \in Y_t^n(a_n)} \left(\frac{n}{a_n t^2}\right)^{(t-1)t} \\
&= |Y_t^n(a_n)| \left(\frac{n}{a_n t^2}\right)^{(t-1)t} \geq \frac{m_n^{t-1}}{(t-1)} \left(\frac{n}{a_n t^2}\right)^{(t-1)t}.
\end{aligned} \tag{5.5}$$

When a_n choose as a value such that $2 \leq a_n \leq 3$, we have

$$\log \left(\frac{m_n^{t-1}}{(t-1)} \left(\frac{n}{a_n t^2}\right)^{(t-1)t} \right) = (t^2 - 1) \log n + O(1) \tag{5.6}$$

because $t - 1 + (t - 1)t = t^2 - 1$. Hence, we obtain (5.1).

6 Conclusion

We have derived general formulas for the mutual information and the logarithm of the number of distinguishable elements when a unitary group representation is given. We have proposed the above quantities as a figure of merit to address the population coding with group representation because these quantities reflect the global information structure unlike Fisher information. Then, we have applied these general formulas to the case with multi-phase estimation and multiple applications of $SU(t)$. As the results, we have revealed that the optimal strategy realized the twice value of the standard case for these two quantities, which can be considered as Heisenberg scaling. We have also shown that the optimal strategies for maximizing Fisher information have much smaller values for these quantities. This fact shows the advantage of our figure of merit over Fisher information.

AppendixA Derivations of (2.18) and (2.19)

Since $f(g')|\psi\rangle\langle\psi|f(g')^\dagger$ is a pure state, the reference [47, (6)] shows the inequality

$$\begin{aligned}\epsilon &\leq 2(M(|\psi\rangle, \epsilon) - 1)^s \operatorname{Tr} \left(\sum_{g' \in \mathcal{X}} P(g') f(g') |\psi\rangle\langle\psi| f(g')^\dagger \right)^{1+s} \\ &\leq 2M(|\psi\rangle, \epsilon)^s \operatorname{Tr} \left(\sum_{g' \in \mathcal{X}} P(g') f(g') |\psi\rangle\langle\psi| f(g')^\dagger \right)^{1+s}\end{aligned}\quad (\text{AppendixA.1})$$

for $0 \leq s \leq 1$ and any distribution P on G . Choosing $\alpha = 1 + s$, we have

$$\log M(|\psi\rangle, \epsilon) \geq S_\alpha \left(\sum_{g' \in \mathcal{X}} P(g') f(g') |\psi\rangle\langle\psi| f(g')^\dagger \right) - \frac{1}{\alpha - 1} (\log 2 - \log \epsilon)$$

(AppendixA.2)

for $1 < \alpha \leq 2$. Taking the maximum for P , we obtain (2.18).

Since $f(g')|\psi\rangle\langle\psi|f(g')^\dagger$ is a pure state, the reference [44, (4.67)] shows the inequality

$$\begin{aligned}&\log(1 - \epsilon) \\ &\leq \max_P \log \operatorname{Tr} \left(\sum_{g' \in \mathcal{X}} P(g') f(g') |\psi\rangle\langle\psi| f(g')^\dagger \right)^{\frac{1}{1-s}} + \frac{s}{1-s} \log M(|\psi\rangle, \epsilon)\end{aligned}\quad (\text{AppendixA.3})$$

for $s < 0$. Choosing $\beta = \frac{1}{1-s}$, we have (2.19).

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